

VISUALIZATION OF NOISE LEVEL MEASUREMENT DATA

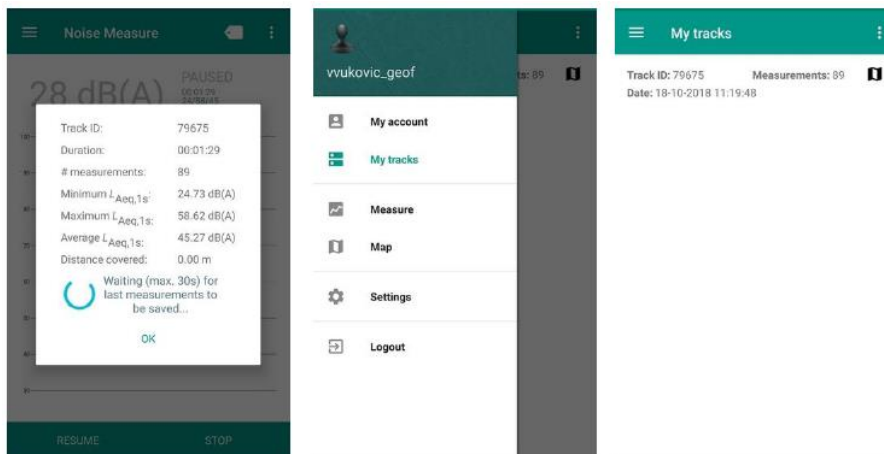
Instructions for collecting and retrieving measurement data

1. Register on www.noisetube.net



The screenshot shows the NoiseTube website's registration page. At the top, there is a navigation menu with links for 'About', 'Cities', 'People', 'Download', 'API', 'Join!', and 'Login'. Below the navigation is the 'Sign up as a new user' section. A note states 'All fields are required.' The form includes input fields for 'Username:', 'Password:' (with a sub-note '(no symbols or spaces please)'), 'Repeat password:', 'E-mail address:', 'Home town:' (with a sub-note '(please write City, Country)'), and 'Mobile phone brand & model:'. There is also a checkbox for 'Are you human?' and a CAPTCHA image. A 'Sign up' button is located at the bottom of the form.

2. Download the NoiseTube Mobile app to your mobile phone. You log in to the application with the data used during registration.
3. Data collection using the NoiseTube application:
 - Before collecting data, it is necessary to enable the measurement to be downloaded to the mobile device, to the NoiseTube server and to enable the application to use the GPS location in the settings of the mobile application.
 - The estimated time for collecting measurement data is about 180 minutes. The application registers the measurement every 1 second. Each student should collect about 10,000 measurements for their area.
 - The recommendation for the duration of one measurement session is 10-15 minutes. Then stop the measurement, wait for it to be saved, and start a new measurement. If the measurements are saved correctly, it will be displayed in the app under *My tracks*.



- Measurements should be collected on weekdays in the morning and afternoon or evening intervals, always for the same period (e.g. measured in the morning from 8 am to 10 am, in the afternoon from 4 pm to 6 pm). Choose the measurement period arbitrarily because it depends on your free time but follow the instructions.
4. All measurements are publicly available at www.noisetube.net within 24 hours. The *Your Elog* menu contains data that needs to be downloaded in .kml format.

The screenshot shows the NoiseTube website interface. At the top, there is a navigation menu with links: About, Cities, People, Download, API, Your Elog, Your Profile, Logout, Help, Publications, and Team. The main content area features a user profile for 'vvukovic_geof' with a profile picture and a 'Daily noise exposure' indicator showing '7'. Below the profile, there are sections for 'Activity' (Last: 19 minutes ago, Total measurements, Total annotations), 'Upload data', 'My tags', and 'Daily noise exposure'. The central part of the page displays a 'Timeline: 2 digital traces of my exposure to noise pollution'. The first trace is marked 'Track not yet processed. Please check again later.' The second trace, from 2018-10-18 08:08:09 UTC to 2018-10-18 08:12:21 UTC, includes a 'Frequent tags' section with a 'Click to load..' link, a 'Measurements' section with details (Duration: 4 minutes, Measurements: 253, Average: 50.8 dB(A), Max: 72.2 | Min: 29.7, Distance covered: 0 m), a line graph showing noise levels over time with 'high', 'moderate', and 'low' indicators, and a map showing the location near 'Muzej iluzija'.

If the measurements do not appear on the specified page, you can find them stored in the phone's memory in .xml format.

During the measurement, the following data were recorded: noise level in decibels, geographical coordinates in the WGS84 reference coordinate system and the date and time of the measurement.

Instructions for processing measurement data and creating a cartographic display in QGIS

Data downloaded in .kml format cannot be processed in QGIS - it needs to be converted to .csv format. Data conversion is possible by "editing" in Notepad or using an online converter <http://konklone.io/json/> or <https://www.convertcsv.com/kml-to-csv.html> (Figure 1).

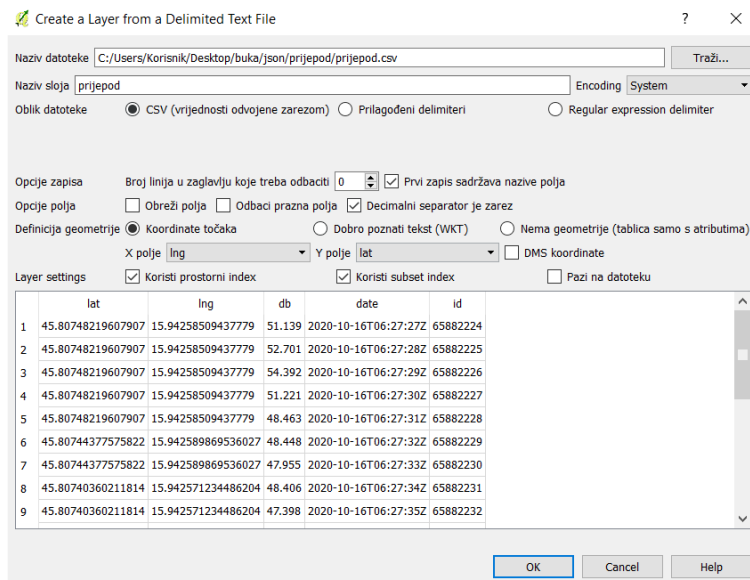


Figure 2. Display of the AddDelimitedTextLayer command window

3. Classification of measurement data

The loaded data must be divided into classes and the corresponding color must be selected (Figure 4 and 5). The presentation obtained in this way must be presented in the technical report (Figure 6).






<code>rgb(0,176,240)</code>		< 30 db
<code>rgb(0,176,80)</code>		31 – 40 db
<code>rgb(255,255,0)</code>		41 – 50 db
<code>rgb(255,102,0)</code>		51 – 60 db
<code>rgb(255,0,0)</code>		> 60 db

Figure 4. Classification groups of input data

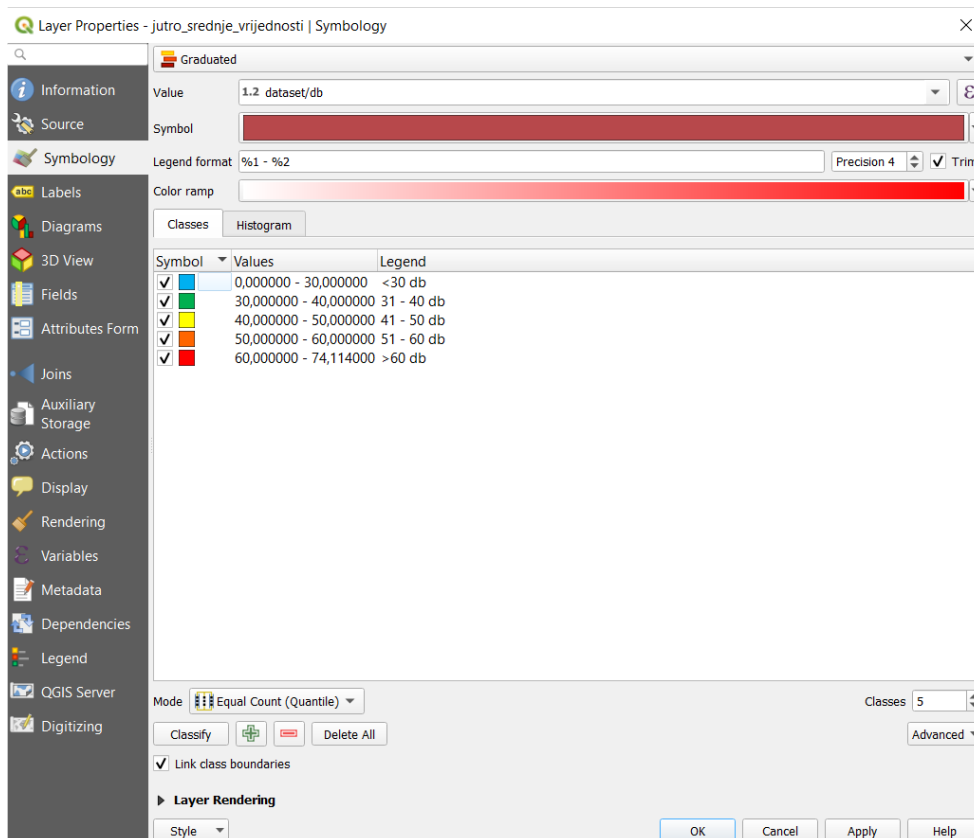


Figure 5. Data classification window



Figure 6. Classified measurement data shown on DOF

4. Setting up a vector grid

The measurement area should be covered by a vector grid (Figure 7) using the command *Vector* → *Research tools* → *Create grid*.

A vector grid is needed for further analysis, i.e. the cross-section of each polygon with measurement data. This way, data can be obtained such as the number of measurements in a particular square and the mean value of the measurements belonging to that square. The size and type of grid for raster interpolation is arbitrary and each student can adjust it to the display on

their project (e.g. a grid of squares with a side length of 2 meters, a grid of hexagons with a side length of 3 meters, etc.).

Note: Use transparency on the map to display the vector grid to identify the background.



Figure 7. Vector grid

5. Classification of mean values of measurements

- a) The calculation of the mean value of the noise level can be performed using the command *Vector → Data management tools → Join attributes by location* (Figure 8).

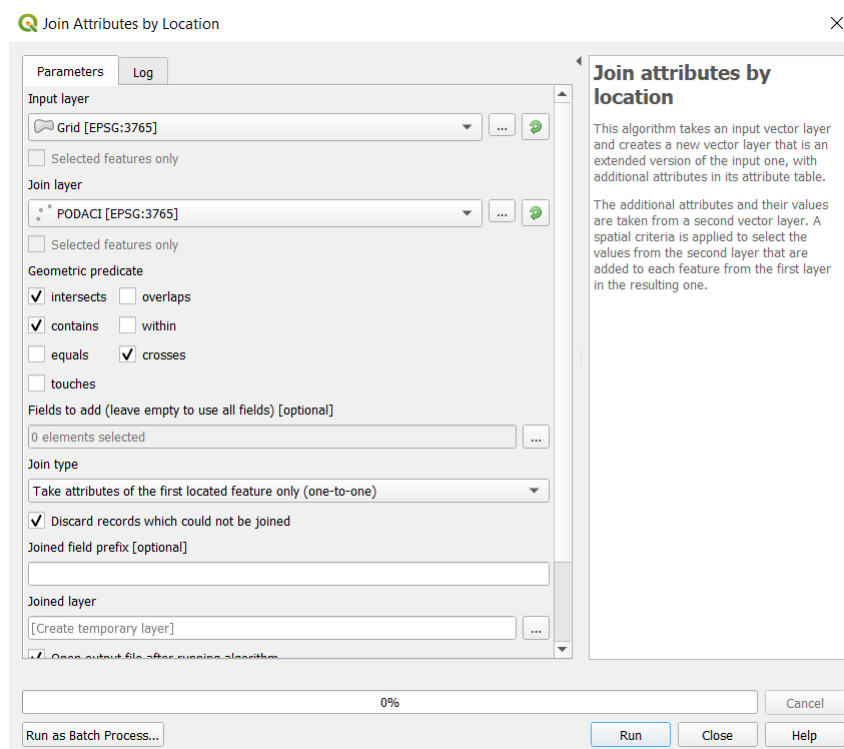


Figure 8. Join attributes by location



Figure 9. Classification of polygons according to mean values

- b) One of the most common interpolation methods is IDW. In the Processing Toolbox search window it was necessary to enter "IDW interpolation " (*Figure 9*).

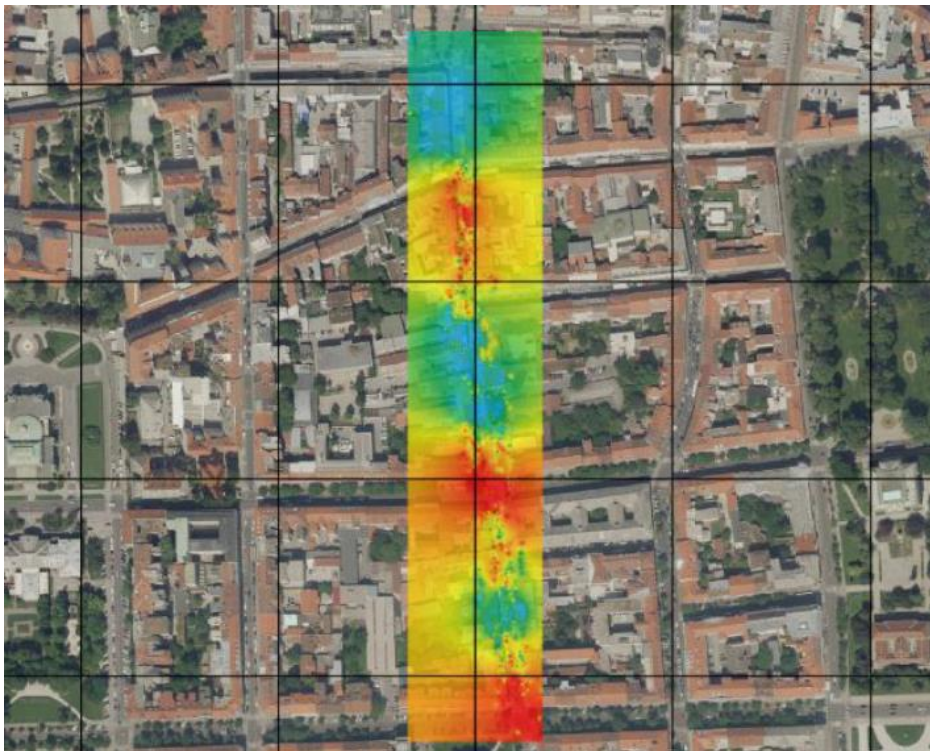


Figure 10. IDW interpolation

c) TIN interpolation

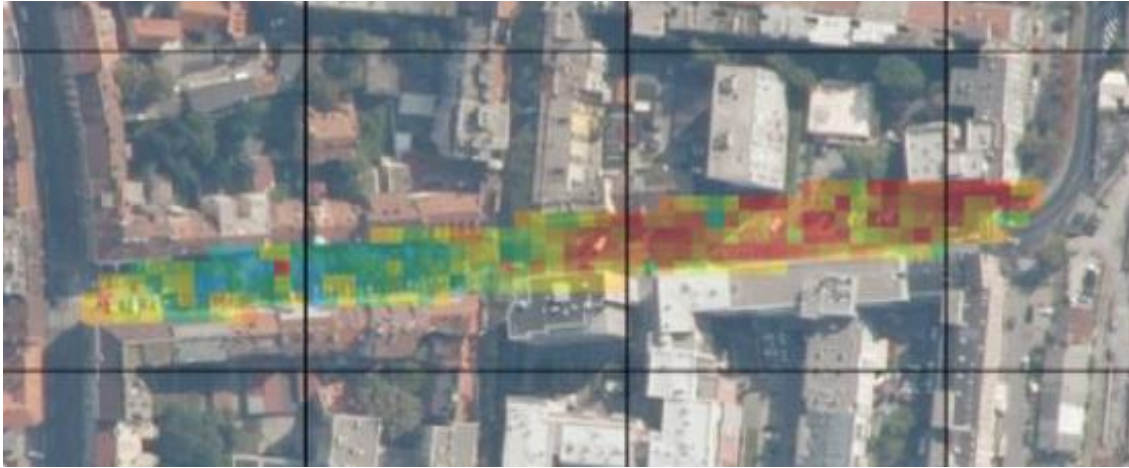


Figure 11. TIN interpolation

6. Creating a map

The map display is done in Map Composer. Process attention to the external content of the map!

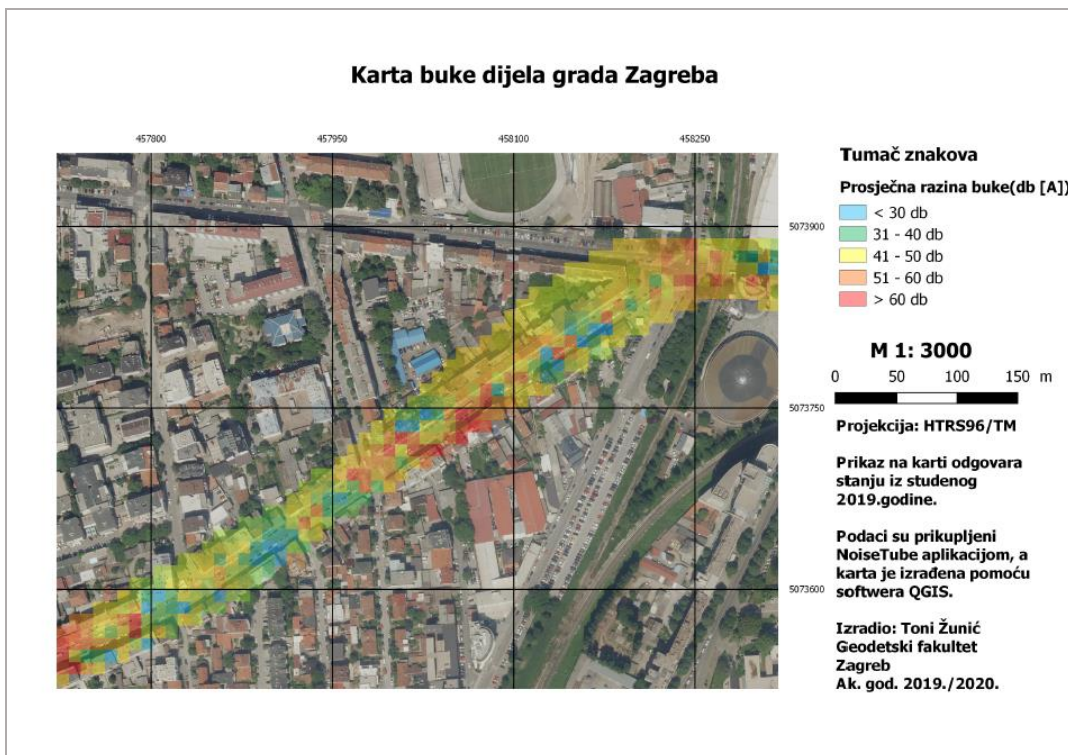


Figure 12. Noise map

Instructions for processing measurement data and creating a map in ArcGIS Online

Data downloaded in .kml format cannot be processed in ArcGIS - it needs to be converted to .csv format, GeoJSON, .gpx or .shp format.

Note: If invalid measurements appear in the data set, they must be dropped before entering them in the program (eg no coordinates are recorded, an extremely high db value is recorded, etc.).

1. Basemap

The Basemap provides the geographical background for the content you want to display on the map. When you create a map, you can choose which background you want to use (*Figure 12*). You can change the background at any time using the map background gallery or your own layer.

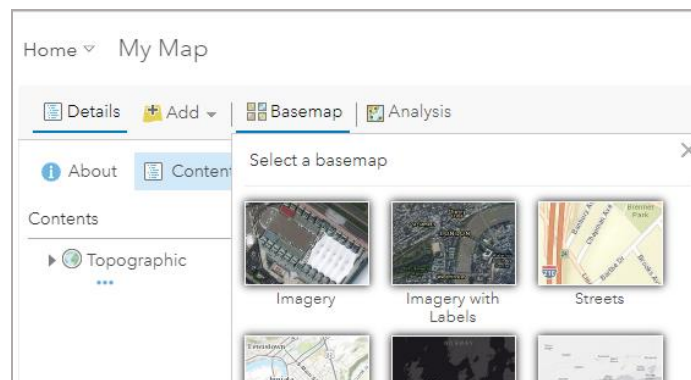


Figure 13. Gallery of available basic maps in ArcGIS Online

2. Upload measurement data to ArcGIS Online

The data can be loaded by selecting the command *Add → Add Layer From File*.

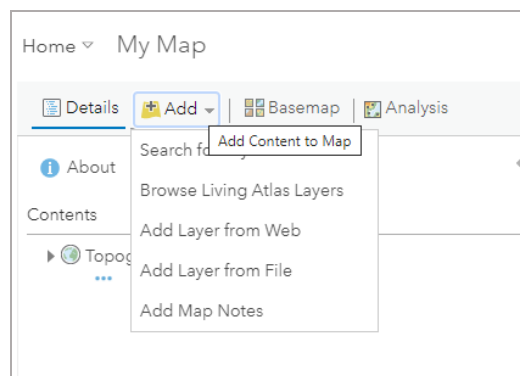


Figure 14. Data Load Menu in ArcGIS Online

3. Classification of measurement data

Loading data opens a layer style change menu. The relevant attribute (decibels) is selected first and then the appropriate data display style. The data should be divided into classes (*Figure 14*).

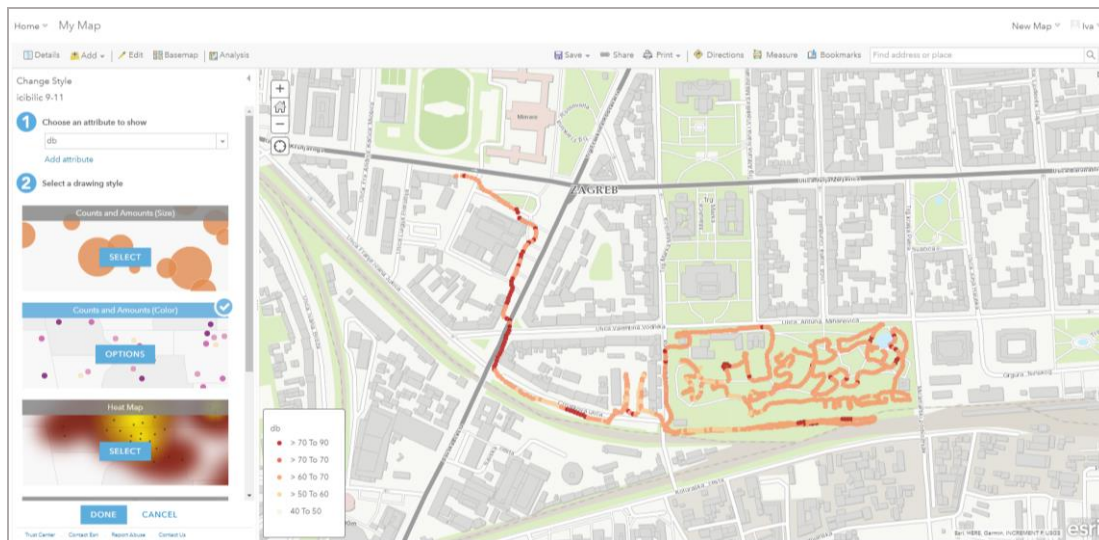


Figure 15. Loaded data layer settings

4. Measurement interpolation

The Analysis menu contains tools that are performed on the selected data. Among them is the *Interpolate points*.

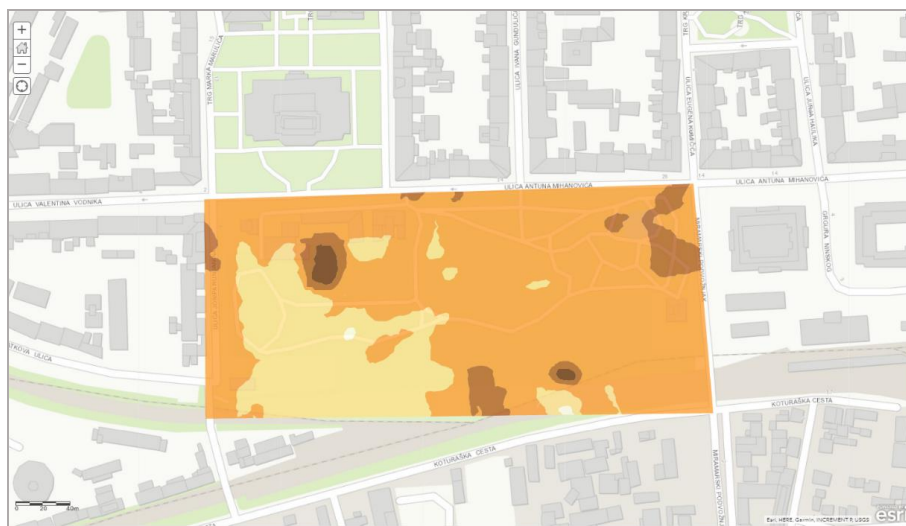


Figure 16. Interpolation result in ArcGIS Online